

INTRODUCTION

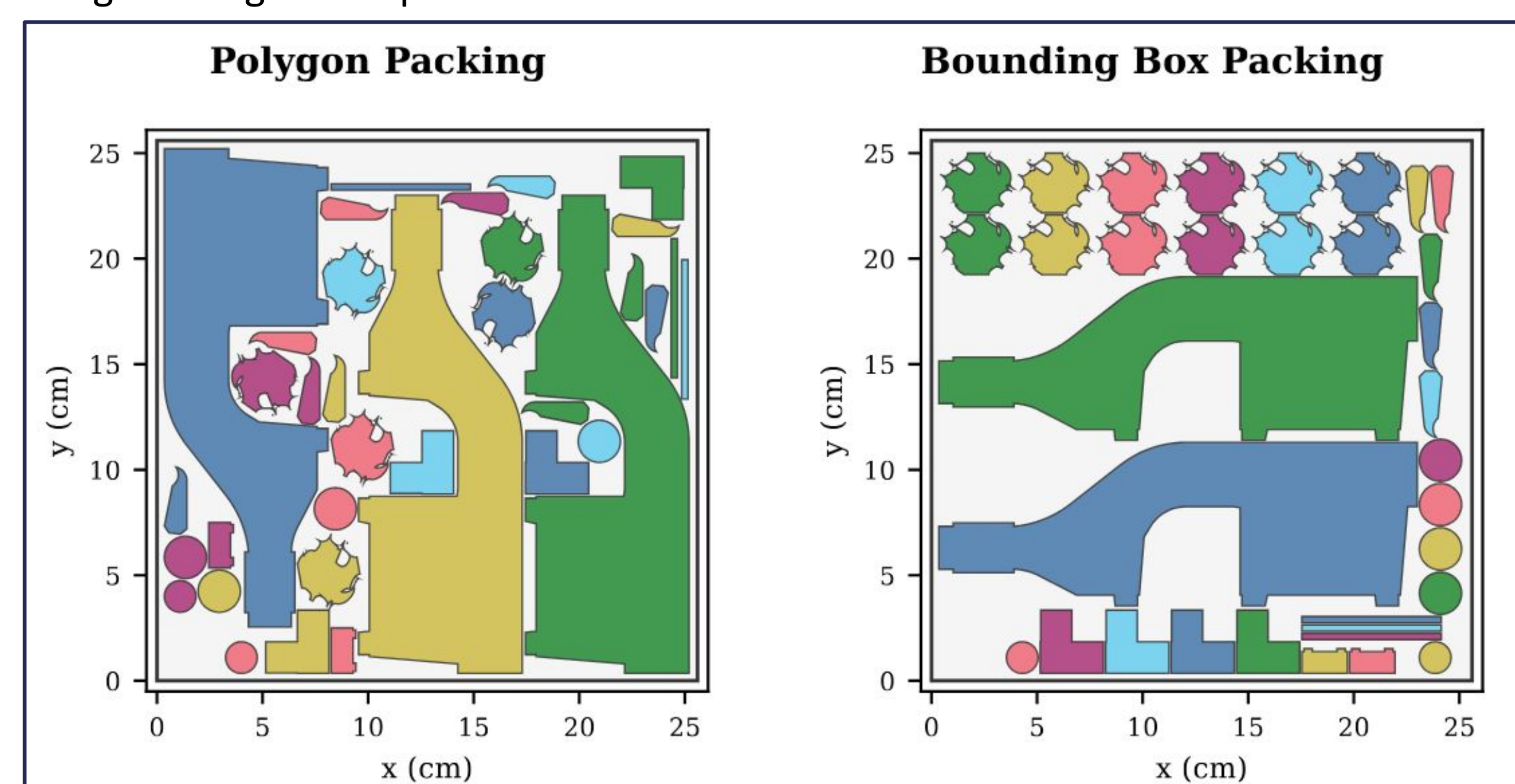
3D printing workflows often require producing multiple parts for a single assembly. A common strategy is to batch parts on one build plate to improve efficiency.

Most packing algorithms optimize for **geometric fit** — not actual print time.

In practice, print time depends on:

- Travel between parts
- Layer-by-layer interactions
- Slicer toolpath behavior

We introduce a **time-aware packing approach** that directly optimizes throughput using a slicing-aware print time model.



Different layouts → different travel paths → different print times

EXPERIMENTAL SETUP

Dataset:

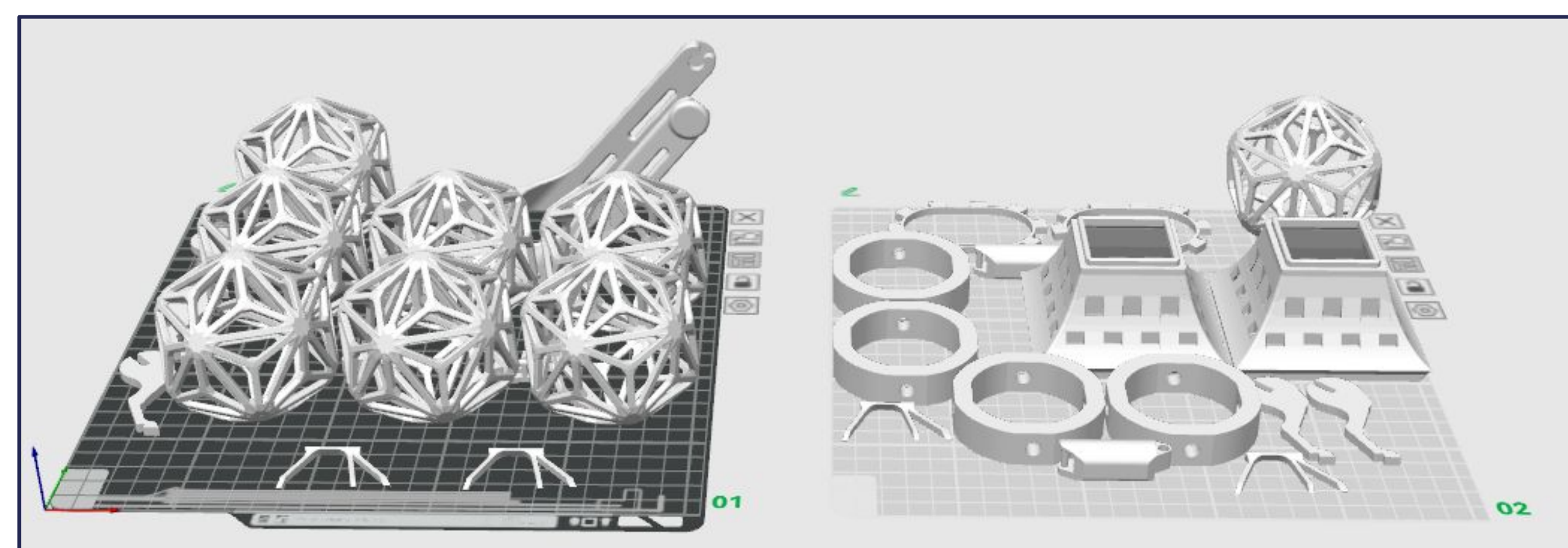
- 4,187 STL models from Thingi10K
- Filtered for Bambu X1C build volume

Build Generation:

- 3–15 unique parts per build
- 10–150 total parts after replication
- Realistic production-style batches

Evaluation:

- Compared packing algorithms:
 - Bounding Box (fast baseline)
 - Polygon Projection (proposed)
 - Large Neighborhood Search (LNS)
- Baseline: PrusaSlicer auto-arrange
- Metric: Throughput = assemblies produced per unit time



APPROACH

Goal:

Maximize throughput over a fixed time horizon

Key Idea:

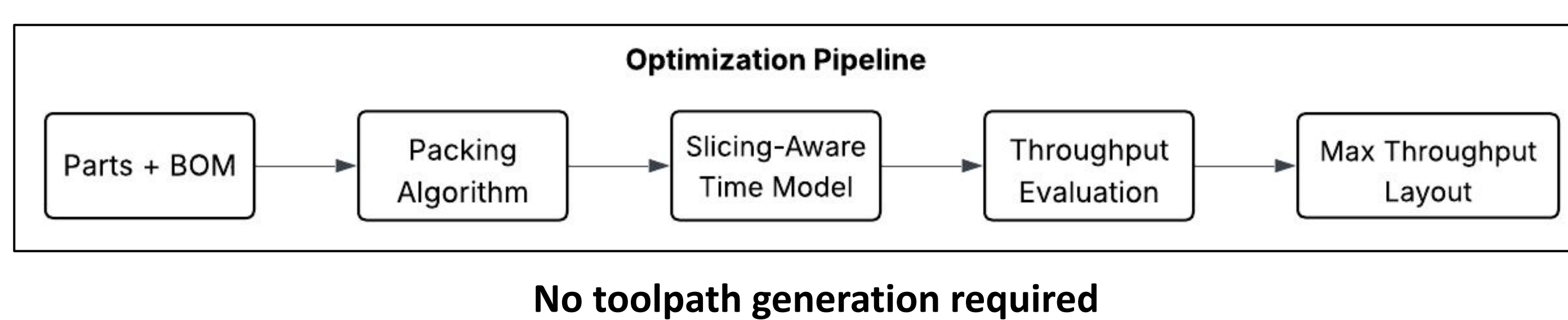
Packing decisions affect print time - not just geometric fit

Pipeline:

1. Select part quantities (x)
2. Generate feasible 2D packing
3. Estimate print time (without toolpath generation)
4. Optimize layout for maximum throughput

Output:

Best packing configuration that maximizes completed assemblies per unit time



ALGORITHM INSIGHTS

Algorithm Insights:

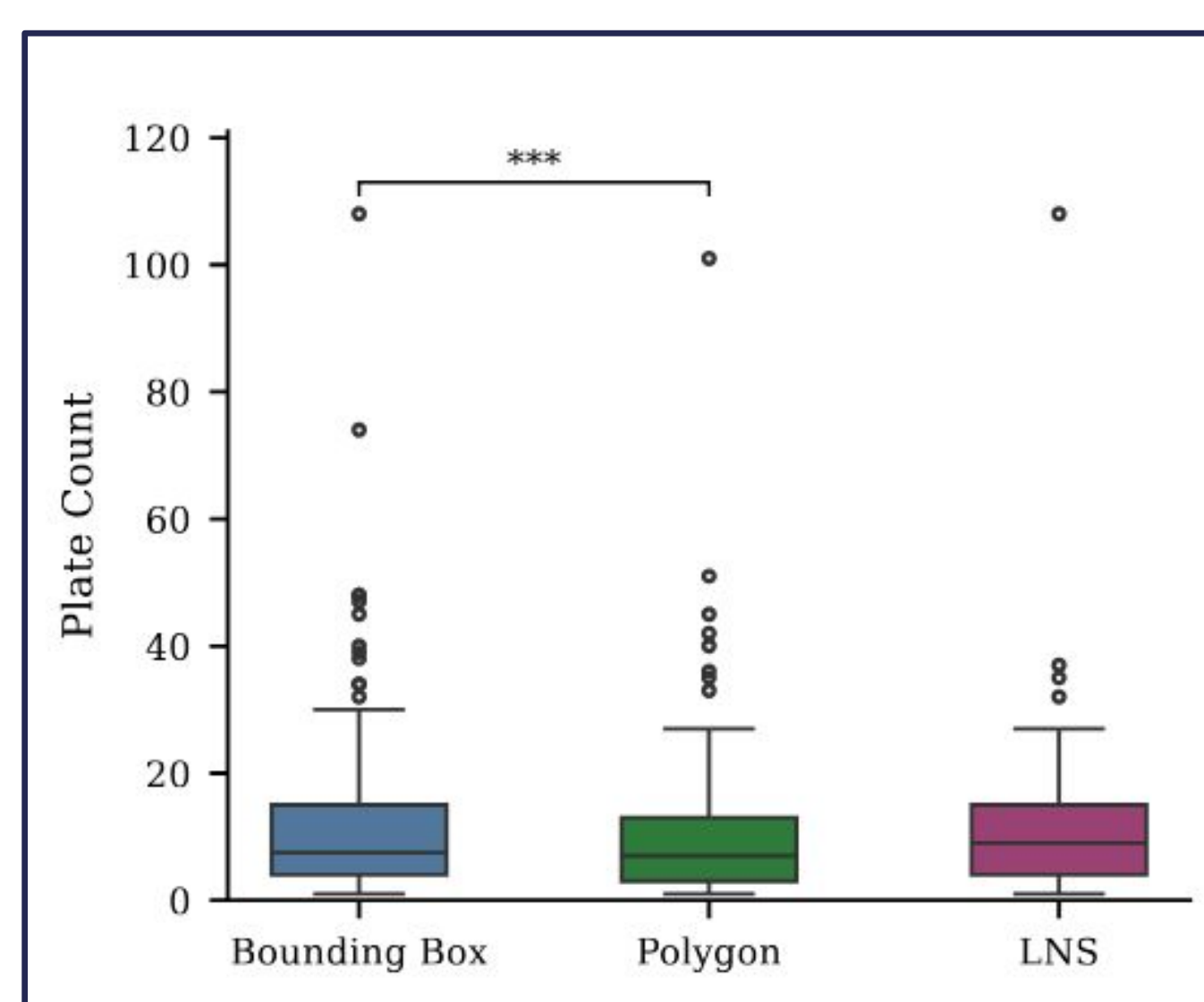
- Bounding Box: **fastest** (<1 s median), but uses **more plates**
- Polygon Projection: **13.5% fewer plates** than Bounding Box
- LNS: ~71 s median compute, no throughput improvement

Key Finding:

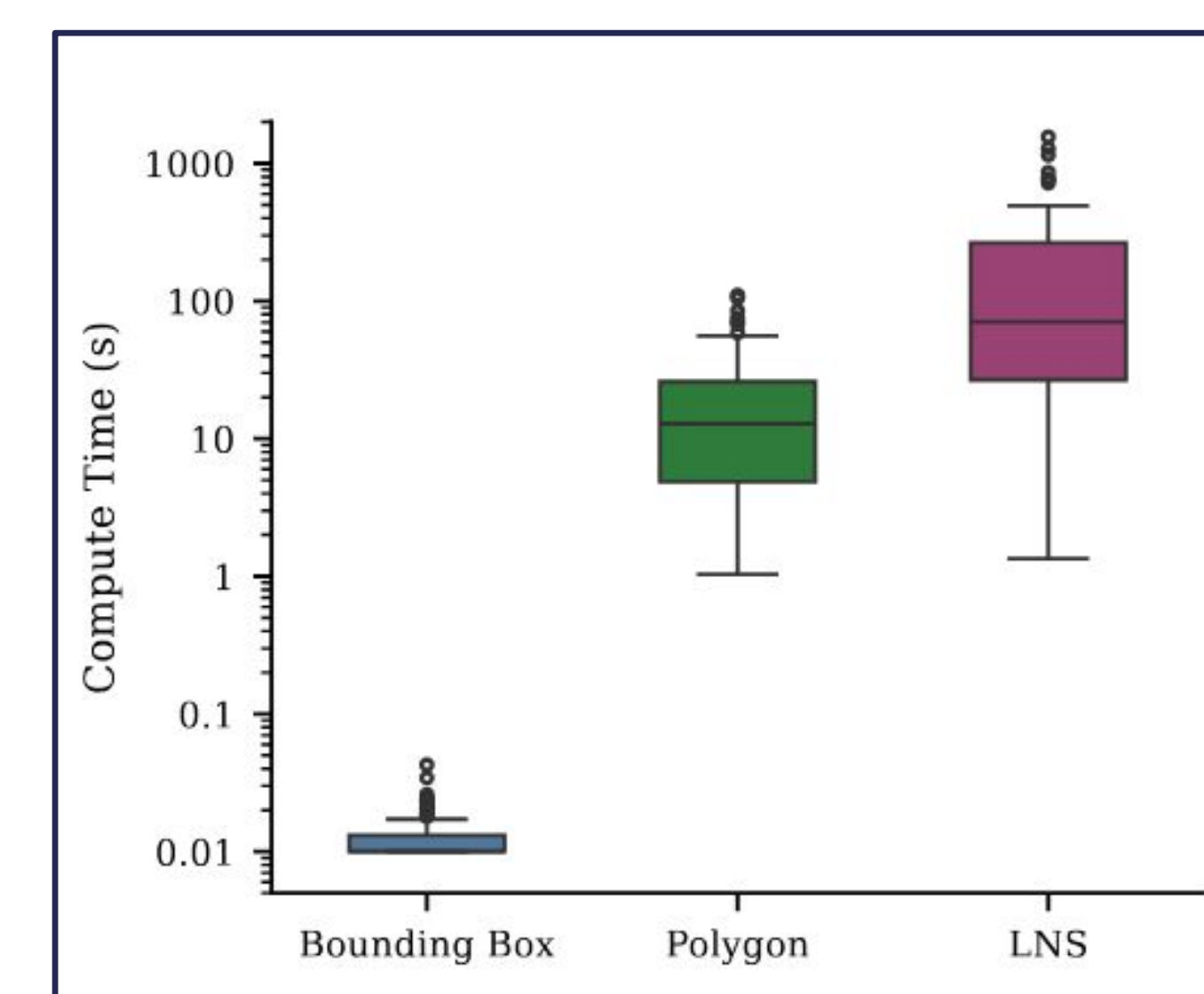
More expensive optimization **did not produce better layouts**.

Why?

Greedy packers already achieve high initial packing density, leaving little room for refinement.



Polygon packing reduces plate count compared to bounding box



LNS is significantly slower with no throughput benefit

For real-world 3D printing:

- Use fast greedy packing methods
- Avoid expensive metaheuristics
- Optimize for print time — not just geometry

→ **Better throughput with minimal compute cost**

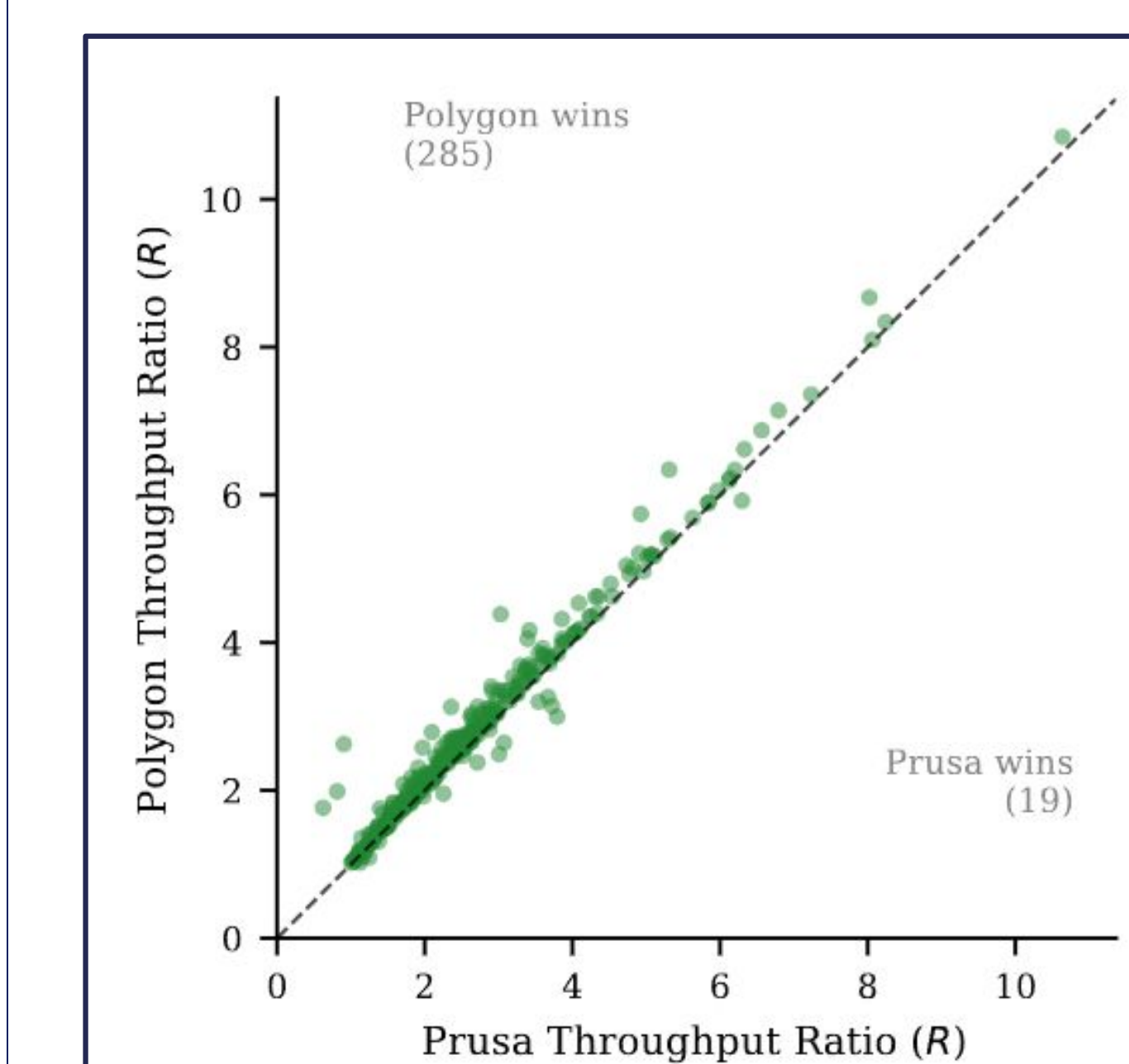
RESULTS

Key Results:

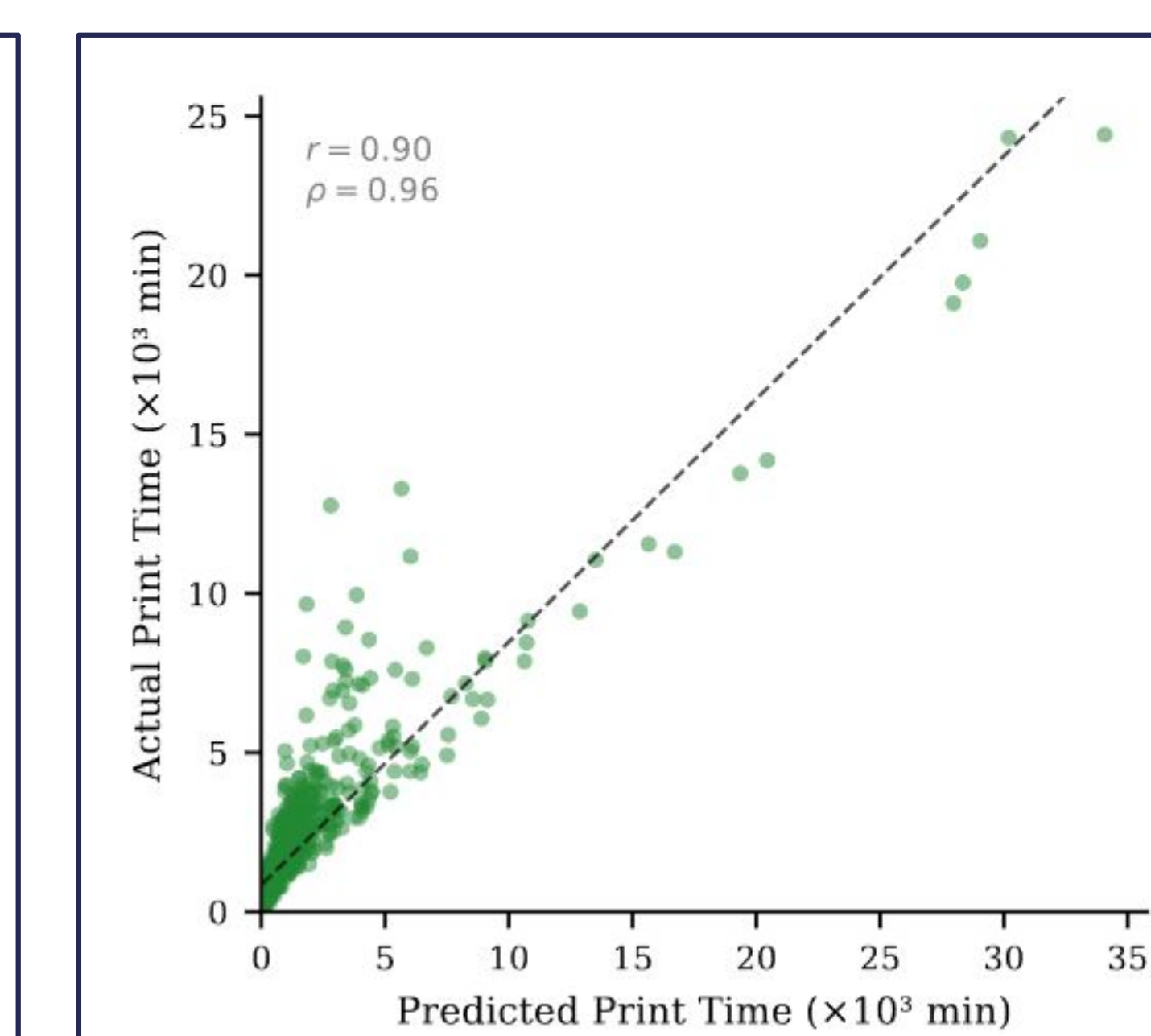
- **+5.7% throughput improvement** (vs Prusa auto-arrange)
- Median savings: **~19.5 min** per build
- Comparable compute time (~3–10 seconds)

Model Validation:

- Strong agreement with slicer estimates
- Pearson $r = 0.90$
- Spearman $\rho = 0.96$



Most builds show improved throughput (points above diagonal)



Strong agreement between predicted and actual print times validates the time model

CONCLUSION

Key Points:

- Time-aware packing improves throughput (+5.7%)
- ~19.5 minutes saved per build
- No toolpath generation required
- Greedy methods are sufficient for high-performance packing.
- Enables faster, more efficient 3D printing workflows.

REFERENCES

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